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Article

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CBN Journal of Applied Statistics

Provided in Cooperation with:

The Central Bank of Nigeria, Abuja

Suggested Citation: Iwueze, Iheanyi S.; Nwogu, Eleazar C.; Ajaraogu, Jude C. (2011) : Best linear unbiased estimate using buys-ballot procedure when trend-cycle component is linear, CBN Journal of Applied Statistics, ISSN 2476-8472, The Central Bank of Nigeria, Abuja, Vol. 02, Iss. 1, pp. 15-30

This Version is available at:

<https://hdl.handle.net/10419/142041>

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Best Linear Unbiased Estimate using Buys-Ballot Procedure when Trend-Cycle Component is Linear

Iheanyi S. Iwueze¹, Eleazar C. Nwogu² and Jude C. Ajaraogu³

The Best linear unbiased estimate (BLUE) of Buys-Ballot estimates when trend-cycle component is linear are discussed in this paper. The estimates are those proposed by Iwueze and Nwogu (2004). Discussed are the Chain Based Estimation (CBE) method and the Fixed Based Estimation (FBE) method. The variates for the CBE method were found to have constant mean and variance but are correlated with only one significant autocorrelation coefficient at lag one. The variates for the FBE method were found to have constant mean, non-constant variance but with constant autocorrelation coefficient at all lags. Because the CBE variates exhibit stationarity, Best Linear unbiased estimators of the slope and intercept were derived. Numerical examples were used to illustrate the methods.

Keywords: Best linear unbiased Estimator, Buys-Ballot derived variables, stationarity, minimum variance, Moving Average Process of order one.

JEL Classification: C22, C32.

Introduction

Iwueze and Nwogu (2004) developed two methods of estimating the parameters of a linear trend-cycle component from the periodic averages of the Buys-Ballot Table (Table 1). The procedure was initially developed for short period series in which the trend-cycle component (M_t) is jointly estimated and can be represented by a linear equation:

$$M_t = a + bt, \quad t = 1, 2, \dots, n \quad (1.1)$$

where a is the intercept, b is the slope and t is the time point.

The two alternative methods are: (i) the Chain Base Estimation (CBE) method which computes the slope from the relative periodic average changes and (ii) the Fixed Base Estimation (FBE) method which computes the slope using the first period as the base period for the periodic average changes.

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For short series in which the trend and cyclical components are jointly estimated, the two contending models for time series decomposition are the additive and multiplicative models (Chatfield (2004), Kendall and Ord (1990)).

Additive model:
$$X_t = M_t + S_t + e_t \tag{1.2}$$

Multiplicative model:
$$X_t = M_t S_t e_t \tag{1.3}$$

where M_t is the trend-cycle component; S_t is the seasonal component with the property that $S_{(i-1)s+j} = S_j, i = 1, 2, \dots, m$, and e_t is the irregular or random component. Results obtained by Iwueze and Nwogu (2004) for the additive and multiplicative models are summarized in Table 2.

It is clear from Table 2 that the trend-cycle estimates are the same for both the additive and multiplicative models. We can also note from Table 2 that estimates of the intercept (a) and the seasonal indices ($S_j, i = 1, 2, \dots, m$) depend on the estimate of the slope (b). This paper will therefore concentrate on the Best Linear Unbiased Estimator (BLUE) of the slope (b) parameter. For the additive model (1.2), it is assumed that the irregular/error component e_t is the Gaussian $N(0, \sigma_1^2)$ white noise, while for the multiplicative model (1.3), e_t is the Gaussian $N(0, \sigma_1^2)$ white noise. For the additive model (1.2), the assumption is that the sum of the seasonal component over a complete period is zero $\left(\sum_{j=0}^s S_j = 0\right)$, while for the multiplicative model (1.3), the sum of the seasonal component over a complete period is $\left(\sum_{j=0}^s S_j = s\right)$.

Table 1: Buys-Ballot Table

p	Season								
	1	2	...	j	...	s	$T_{.i}$	$\bar{X}_{.i}$	$\hat{\sigma}_{.i}$
1	X_1	X_2	...	X_j	...	X_s	$T_{.1}$	$\bar{X}_{.1}$	$\hat{\sigma}_{.1}$
2	X_{s+1}	X_{s+2}	...	X_{s+j}	...	X_{2s}	$T_{.2}$	$\bar{X}_{.2}$	$\hat{\sigma}_{.2}$
3	X_{2s+1}	X_{2s+2}	...	X_{2s+j}	...	X_{3s}	$T_{.3}$	$\bar{X}_{.3}$	$\hat{\sigma}_{.3}$
...
i	$X_{(i-1)s+1}$	$X_{(i-1)s+2}$...	$X_{(i-1)s+j}$...	$X_{(i-1)s+s}$	$T_{.i}$	$\bar{X}_{.i}$	$\hat{\sigma}_{.i}$
...
m	$X_{(m-1)s+1}$	$X_{(m-1)s+2}$...	$X_{(m-1)s+j}$...	X_{ms}	$T_{.m}$	$\bar{X}_{.m}$	$\hat{\sigma}_{.m}$
$T_{.j}$	$T_{.1}$	$T_{.2}$...	$T_{.j}$...	$T_{.s}$	$T_{..}$		
$\bar{X}_{.j}$	$\bar{X}_{.1}$	$\bar{X}_{.2}$...	$\bar{X}_{.j}$...	$\bar{X}_{.s}$		$\bar{X}_{..}$	
$\hat{\sigma}_{.j}$	$\hat{\sigma}_{.1}$	$\hat{\sigma}_{.2}$...	$\hat{\sigma}_{.j}$...	$\hat{\sigma}_{.s}$			$\hat{\sigma}_{..}$

$$\begin{aligned}
 T_{i.} &= \sum_{j=1}^s X_{(i-1)s+j}, \quad i=1, 2, \dots, m & \bar{X}_{i.} &= \frac{T_{i.}}{s} = \frac{1}{s} \sum_{j=1}^s X_{(i-1)s+j}, \quad i=1, 2, \dots, m; \\
 T_{.j} &= \sum_{i=1}^m X_{(i-1)s+j}, \quad j=1, 2, \dots, s & \bar{X}_{.j} &= \frac{T_{.j}}{m} = \frac{1}{m} \sum_{i=1}^m X_{(i-1)s+j}, \quad j=1, 2, \dots, s; \\
 T_{..} &= \sum_{i=1}^m T_{i.} = \sum_{j=1}^s T_{.j} = \sum_{i=1}^m \sum_{j=1}^s X_{(i-1)s+j}; & \bar{X}_{..} &= \frac{T_{..}}{ms} = \frac{T_{..}}{ms}, \quad n = ms \\
 \hat{\sigma}_{i.} &= \sqrt{\frac{1}{s-1} \sum_{j=1}^s (X_{(i-1)s+j} - \bar{X}_{i.})^2}, \quad i=1, 2, \dots, m; & \hat{\sigma}_{.j} &= \sqrt{\frac{1}{m-1} \sum_{i=1}^m (X_{(i-1)s+j} - \bar{X}_{.j})^2}, \quad j=1, 2, \dots, s \\
 \hat{\sigma} &= \sqrt{\frac{1}{n-1} \sum_{i=1}^m \sum_{j=1}^s (X_{(i-1)s+j} - \bar{X}_{..})^2}
 \end{aligned}$$

Table 2: Buys-Ballot estimates for linear trend.

	Additive model (1.2)	Multiplicative model (1.3)
$T_{i.}$	$as + \frac{bs}{2}[(2i-1)s+1]$	$as + \frac{bs}{2}[(2i-1)s+1]$
$\bar{X}_{i.}$	$a + \frac{b}{2}[(2i-1)s+1]$	$a + \frac{b}{2}[(2i-1)s+1]$
$T_{.j}$	$ma + \frac{mb}{2}[2j+n-s] + mS_j$	$\left[ma + \frac{mb}{2}(2j+n-s) \right] S_j$
$\bar{X}_{.j}$	$a + \frac{b}{2}[2j+n-s] + S_j$	$\left[a + \frac{b}{2}(2j+n-s) \right] S_j$
$T_{..}$	$na + \frac{nb}{2}[n+1]$	$na + \frac{nb}{2}[n+1]$
$\bar{X}_{..}$	$a + \frac{b}{2}[n+1]$	$a + \frac{b}{2}[n+1]$
$\hat{b}(\text{CBE})$	$\frac{\bar{X}_{m.} - \bar{X}_{1.}}{n-s}$	$\frac{\bar{X}_{m.} - \bar{X}_{1.}}{n-s}$
$\hat{b}(\text{FBE})$	$\frac{1}{n-s} \sum_{i=2}^m \left(\frac{\bar{X}_{i.} - \bar{X}_{1.}}{i-1} \right)$	$\frac{1}{n-s} \sum_{i=2}^m \left(\frac{\bar{X}_{i.} - \bar{X}_{1.}}{i-1} \right)$
\hat{a}	$\bar{X}_{..} - \frac{\hat{b}}{2}[n+1]$	$\bar{X}_{..} - \frac{\hat{b}}{2}[n+1]$
S_j	$X_{.j} - \left[\bar{X}_{..} + \frac{\hat{b}}{2}(2j-s-1) \right]$	$X_{.j} / \left[\bar{X}_{..} + \frac{\hat{b}}{2}(2j-s-1) \right]$

The multiplicative model (1.3) can be linearized to become the additive model (1.4)

$$X_t^* = M_t^* + S_t^* + e_t^*, \quad t = 1, 2, \dots, n \tag{1.4}$$

where $X_t^* = \log_e X_t$, $M_t^* = \log_e M_t$, $S_t^* = \log_e S_t$, $e_t^* = \log_e e_t$. The behaviour of $M_t^* = \log_e M_t$ when M_t is represented by a linear equation (1.1) have been studied by Iwueze and Akpanta

(2007) and it was shown that for $-0.01 \leq b/a \leq 0.06$, M_t^* could still be represented by a straight line $M_t^* = \alpha + \beta t$, with $\alpha = \log_e a$ and $\beta = b/a$. The behaviour of $S_t^* = \log_e S_t$ to achieve $\left(\sum_{j=0}^s S_j = s\right)$ have been studied by Iwueze et al (2008). The behaviour of $e_t^* = \log_e e_t$ for $e_t^* \sim N(0, \sigma^2)$ when $e_t \sim N(1, \sigma^2)$ have been studied by Iwueze (2007) and it was shown that the logarithmic transform of the left-truncated $N(1, \sigma^2)$ distribution is approximately normal when $\sigma < 0.1$. It follows that we can study the additive model (1.1) and apply the results obtain to the multiplicative model after linearization.

The main objective of this paper is to obtain the BLUE of the slope parameter for the additive model. Section 2 presents the covariance structure of CBE derived variables, while Section 3 presents the covariance structure of the FBE derived variables. Section 4 contains the determination of the BLUE for the CBE estimate of the slope parameter. Section 5 presents the simple average of the CBE derived variables, Section 6 contains the numerical examples while Section 7 contains the concluding remarks.

2. Covariance Analysis of the CBE Derived Variables: Additive Model

Under the CBE method, the estimate of the slope (\hat{b}) was calculated as the average of $\hat{b}_i^{(c)}$, $i = 1, 2, \dots, m-1$ given by Iwueze and Nwogu (2004) as:

$$\hat{b}_i^{(c)} = \frac{\bar{X}_{(i+1)} - \bar{X}_i}{s}, i = 1, 2, \dots, m-1 \quad (2.1)$$

For the additive model the assumption is that the irregular components are independent and identically normally distributed with mean zero and common variance $\sigma_1^2 = \sigma^2 [e_t \sim N(0, \sigma^2)]$.

Under this assumption, $\bar{e}_i \sim N\left(0, \frac{\sigma^2}{s}\right)$, $\bar{e}_j \sim N\left(0, \frac{\sigma^2}{m}\right)$, $\bar{e}_{..} \sim N\left(0, \frac{\sigma^2}{n}\right)$.

Using (1.2), the periodic averages are given by

$$\bar{X}_i = a + \frac{b}{2}[(2i-1)s+1] + \bar{e}_i, i = 1, 2, \dots, m \quad (2.2)$$

Hence, our variable of interest is now given by

$$\hat{b}_i^{(c)} = \frac{1}{s}(\bar{X}_{(i+1)} - \bar{X}_i) = b + \frac{1}{s}(\bar{e}_{(i+1)} - \bar{e}_i), i = 1, 2, \dots, m-1 \quad (2.3)$$

Therefore, the expected value and variance of $\hat{b}_i^{(c)}$ are

$$E(\hat{b}_i^{(c)}) = E(b) + \frac{1}{s} E(\bar{e}_{(i+1)} - \bar{e}_i) = b \tag{2.4}$$

$$\begin{aligned} \text{var}(\hat{b}_i^{(c)}) &= \sigma_{\hat{b}_i^{(c)}}^2 = E\left[\left(\hat{b}_i^{(c)} - b\right)^2\right] = \frac{1}{s^2} E\left[\left(\bar{e}_{(i+1)} - \bar{e}_i\right)^2\right] \\ &= \frac{2\sigma^2}{s^3} \end{aligned} \tag{2.5}$$

The covariance between $\hat{b}_i^{(c)}$ and $\hat{b}_j^{(c)}$ is

$$\begin{aligned} \text{cov}(\hat{b}_i^{(c)}, \hat{b}_j^{(c)}) &= \sigma_{ij} = E\left[\left(\hat{b}_i^{(c)} - E(\hat{b}_i^{(c)})\right)\left(\hat{b}_j^{(c)} - E(\hat{b}_j^{(c)})\right)\right] \\ &= \frac{1}{s^2} E\left[\left(\bar{e}_{(i+1)} - \bar{e}_i\right)\left(\bar{e}_{(j+1)} - \bar{e}_j\right)\right] \\ &= \frac{1}{s^2} E\left[\bar{e}_{(i+1)}\bar{e}_{(j+1)} - \bar{e}_{(i+1)}\bar{e}_j - \bar{e}_i\bar{e}_{(j+1)} + \bar{e}_i\bar{e}_j\right] \end{aligned} \tag{2.6}$$

For $j = i + 1$,

$$\sigma_{ij} = \frac{-1}{s^2} E(\bar{e}_{(i+1)}^2) = \frac{-1}{s^2} \left(\frac{\sigma^2}{s}\right) = \frac{-\sigma^2}{s^3} \tag{2.7}$$

For $j = i - 1$,

$$\sigma_{ij} = \frac{-1}{s^2} E(\bar{e}_i^2) = \frac{-1}{s^2} \left(\frac{\sigma^2}{s}\right) = \frac{-\sigma^2}{s^3} \tag{2.8}$$

For $j = i \pm k, k > 1$,

$$\sigma_{ij} = 0 \tag{2.9}$$

In summary, let $R(k) = \text{cov}(\hat{b}_i^{(c)}, \hat{b}_{(i-k)}^{(c)})$ and $\rho_k = R(k)/R(0)$. The results (2.5) through (2.9) can be summaries as follows.

$$R(k) = \begin{cases} 2\sigma^2 / s^3, & k = 0 \\ -\sigma^2 / s^3, & k = \pm 1 \\ 0, & k > 1 \end{cases} \tag{2.10}$$

$$\rho_k = \begin{cases} 1, & k = 0 \\ -1/2, & k = \pm 1 \\ 0, & k > 1 \end{cases} \tag{2.11}$$

We have shown that the sequence, $\hat{b}_i^{(c)}, i = 1, 2, \dots, m - 1$, of CBE derived variables have the covariance structure of a moving average process of order one (MA(1)). For more details on MA(1) processes, see Box et al (1994), Chatfield (2004).

3. Covariance Analysis of the FBE Derived Variables: Additive Model

Under the FBE method, the estimate of the slope (\hat{b}) was calculated as the average of $\hat{b}_i^{(f)}$, $i = 1, 2, \dots, m - 1$ given by Iwueze and Nwogu (2004) as:

$$\hat{b}_i^{(f)} = \frac{\bar{X}_{(i+1).} - \bar{X}_{1.}}{(i-1)s}, \quad i = 1, 2, \dots, m - 1 \quad (3.1)$$

Using (1.2),

$$\hat{b}_i^{(f)} = \frac{\bar{X}_{(i+1).} - \bar{X}_{1.}}{(i-1)s} = b + \frac{\bar{e}_{(i+1).} - \bar{e}_{1.}}{(i-1)s}, \quad i = 1, 2, \dots, m - 1 \quad (3.2)$$

Hence, the expected value and variance of $b_i^{(f)}$ are

$$E(\hat{b}_i^{(f)}) = E(b) + \frac{1}{(i-1)s} E(\bar{e}_{(i+1).} - \bar{e}_{1.}) = b \quad (3.3)$$

$$\begin{aligned} \text{var}(\hat{b}_i^{(f)}) &= \sigma_{\hat{b}_i^{(f)}}^2 = E\left[(\hat{b}_i^{(f)} - b)^2 \right] = \frac{1}{(i-1)^2 s^2} E\left[(\bar{e}_{(i+1).} - \bar{e}_{1.})^2 \right] \\ &= \frac{2\sigma^2}{(i-1)^2 s^3} \end{aligned} \quad (3.4)$$

$$\begin{aligned} \text{cov}(\hat{b}_i^{(f)}, \hat{b}_j^{(f)}) &= \sigma_{ij} = E\left[(\hat{b}_i^{(f)} - E(\hat{b}_i^{(f)}))(\hat{b}_j^{(f)} - E(\hat{b}_j^{(f)})) \right] \\ &= E\left[(\hat{b}_i^{(f)} - b)(\hat{b}_j^{(f)} - b) \right] \\ &= \frac{1}{(i-1)(j-1)s^2} E\left[(\bar{e}_{(i+1).} - \bar{e}_{1.})(\bar{e}_{(j+1).} - \bar{e}_{1.}) \right] \\ &= \frac{1}{(i-1)(j-1)s^2} E\left[\bar{e}_{(i+1).}\bar{e}_{(j+1).} - \bar{e}_{(i+1).}\bar{e}_{1.} - \bar{e}_{1.}\bar{e}_{(j+1).} + \bar{e}_{1.}^2 \right] \end{aligned} \quad (3.5)$$

For $j = i + k$,

$$\sigma_{ij} = \frac{1}{(i-1)(j-1)s^2} E(\bar{e}_{1.}^2) = \frac{\sigma^2}{(i-1)(j-1)s^2} \quad (3.6)$$

Hence, the autocovariance and autocorrelation structures are:

$$R(k) = \begin{cases} \frac{2\sigma^2}{(i-1)^2 s^3}, & k = 0 \\ \frac{\sigma^2}{(i-1)(j-1)s^3}, & k \neq 0 \end{cases} \quad (3.7)$$

$$\rho_k = \begin{cases} 1, & k = 0 \\ 1/2, & k = \pm 1, \pm 2, \dots \end{cases} \quad (3.8)$$

We have shown that the sequence, $\hat{b}_i^{(f)}, i = 2, 3, \dots, m$, of FBE derived variables are not stationary and their average as an estimate of slope (b), will not give a reliable estimate in its present state.

4. Best linear unbiased estimate of slope (b) using the CBE derived variables

The CBE derived variables $(\hat{b}_i^{(c)}, i = 1, 2, \dots, m - 1)$ have been shown to be stationary and can be used for estimation, while the FBE derived variables $(\hat{b}_i^{(f)}, i = 1, 2, \dots, m - 1)$ are not stationary and estimates based on them will not be reliable. The sequence of CBE derived random variables $\hat{b}_i^{(c)}, i = 1, 2, \dots, m - 1$, are found to have the covariance structure of a first-order moving average process (MA(1) process) with the autocorrelation function given by (2.11).

Let a_1, a_2, \dots, a_{m-1} be any set of real numbers. A linear estimate of the mean $b = E(\hat{b}_i^{(c)})$ is given by

$$T = \sum_{i=1}^{m-1} a_i \hat{b}_i^{(c)} \quad (4.1)$$

If T is unbiased, we obtain that

$$E(T) = \sum_{i=1}^{m-1} a_i E(\hat{b}_i^{(c)}) = \sum_{i=1}^{m-1} a_i b = b \sum_{i=1}^{m-1} a_i = b \quad (4.2)$$

T is unbiased if and only if

$$\sum_{i=1}^{m-1} a_i = 1 \quad (4.3)$$

The variance of T is given by

$$\text{var}(T) = \sum_{i=1}^{m-1} a_i^2 \text{var}(Y_i) + 2 \sum_{i < j} a_i a_j \text{cov}(Y_i, Y_j) \quad (4.4)$$

For the second order stationary sequence of random variables $\hat{b}_i^{(c)}$, $i = 1, 2, \dots, m-1$, with autocorrelation structure (2.11), $\text{var}(T)$ can be written as

$$\text{var}(T) = R(0) \sum_{i=1}^{m-1} a_i^2 + 2R(1) \sum_{i=1}^{m-2} a_i a_{i+1} \quad (4.5)$$

$$= R(0) \left\{ \sum_{i=1}^{m-1} a_i^2 + 2\rho_1 \sum_{i=1}^{m-2} a_i a_{i+1} \right\}$$

$$= R(0) \left\{ \sum_{i=1}^{m-1} a_i^2 - \sum_{i=1}^{m-2} a_i a_{i+1} \right\}$$

$$= \left(\frac{2\sigma^2}{s^3} \right) \left\{ \sum_{i=1}^{m-1} a_i^2 - \sum_{i=1}^{m-2} a_i a_{i+1} \right\} \quad (4.6)$$

Linear unbiased estimates of b that have minimum variance (among all linear unbiased estimates) are called best linear unbiased estimates (BLUE.s). Let

$$S(\mathbf{a}) = \sum_{i=1}^{m-1} a_i^2 - \sum_{i=1}^{m-2} a_i a_{i+1} \quad (4.7)$$

From (4.6), $\min(\text{var}(T)) = R(0) \min(S(\mathbf{a}))$. Hence, the BLUE of b is obtained if we choose a_1, a_2, \dots, a_{m-1} that minimize $S(\mathbf{a})$ with respect to the constraint $\sum_{t=1}^{m-1} a_t = 1$. However, when

$\rho_k = 0$, for all k , $a_i = \frac{1}{m-1}$ (see Rohatgi (1976)).

As an example of the minimization of (4.7) subject to the constraint $\sum_{i=1}^{m-1} a_i = 1$, we let

$m-1 = 10 \Rightarrow m = 11$. Equation (4.7) reduces to

$$\begin{aligned} S(\mathbf{a}) &= a_1^2 + a_2^2 + a_3^2 + a_4^2 + a_5^2 + a_6^2 + a_7^2 + a_8^2 + a_9^2 \\ &+ \left(1 - a_1 - a_2 - a_3 - a_4 - a_5 - a_6 - a_7 - a_8 - a_9\right)^2 \\ &- a_1 a_2 - a_2 a_3 - a_3 a_4 - a_4 a_5 - a_5 a_6 - a_6 a_7 - a_8 a_9 \\ &- a_9 \left(1 - a_1 - a_2 - a_3 - a_4 - a_5 - a_6 - a_7 - a_8 - a_9\right) \end{aligned} \quad (4.8)$$

By equating $\partial S(\mathbf{a})/\partial a_j = 0$, we obtain the system of linear equations given in (4.9).

$$\begin{aligned}
 4a_1 + a_2 + 2a_3 + 2a_4 + 2a_5 + 2a_6 + 2a_7 + 2a_8 + 3a_9 &= 2 \\
 a_1 + 4a_2 + a_3 + 2a_4 + 2a_5 + 2a_6 + 2a_7 + 2a_8 + 3a_9 &= 2 \\
 2a_1 + a_2 + 4a_3 + a_4 + 2a_5 + 2a_6 + 2a_7 + 2a_8 + 3a_9 &= 2 \\
 2a_1 + 2a_2 + a_3 + 4a_4 + a_5 + 2a_6 + 2a_7 + 2a_8 + 3a_9 &= 2 \\
 2a_1 + 2a_2 + 2a_3 + a_4 + 4a_5 + a_6 + 2a_7 + 2a_8 + 3a_9 &= 2 \\
 2a_1 + 2a_2 + 2a_3 + 2a_4 + a_5 + 4a_6 + a_7 + 2a_8 + 3a_9 &= 2 \\
 2a_1 + 2a_2 + 2a_3 + 2a_4 + 2a_5 + a_6 + 4a_7 + a_8 + 3a_9 &= 2 \\
 2a_1 + 2a_2 + 2a_3 + 2a_4 + 2a_5 + 2a_6 + a_7 + 4a_8 + 2a_9 &= 2 \\
 3a_1 + 3a_2 + 3a_3 + 3a_4 + 3a_5 + 3a_6 + 3a_7 + 2a_8 + 6a_9 &= 3
 \end{aligned}
 \tag{4.9}$$

We put the system of linear equations (4.9) in matrix form, to obtain

$$\begin{pmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \\ a_5 \\ a_6 \\ a_7 \\ a_8 \\ a_9 \end{pmatrix} = \begin{pmatrix} 4 & 1 & 2 & 2 & 2 & 2 & 2 & 2 & 3 \\ 1 & 4 & 1 & 2 & 2 & 2 & 2 & 2 & 3 \\ 2 & 1 & 4 & 1 & 2 & 2 & 2 & 2 & 3 \\ 2 & 2 & 1 & 4 & 1 & 2 & 2 & 2 & 3 \\ 2 & 2 & 2 & 1 & 4 & 1 & 2 & 2 & 3 \\ 2 & 2 & 2 & 2 & 1 & 4 & 1 & 2 & 3 \\ 2 & 2 & 2 & 2 & 2 & 1 & 4 & 1 & 3 \\ 2 & 2 & 2 & 2 & 2 & 2 & 1 & 4 & 2 \\ 3 & 3 & 3 & 3 & 3 & 3 & 3 & 2 & 6 \end{pmatrix}^{-1} \begin{pmatrix} 2 \\ 2 \\ 2 \\ 2 \\ 2 \\ 2 \\ 2 \\ 2 \\ 3 \end{pmatrix}
 \tag{4.10}$$

Evaluating (4.10) with $a_{10} = 1 - a_1 - a_2 - a_3 - a_4 - a_5 - a_6 - a_7 - a_8 - a_9$, we obtained the following weights:

$$\begin{aligned}
 a_1 &= 0.046; a_2 = 0.082; a_3 = 0.109; a_4 = 0.127; a_5 = 0.136; a_7 = 0.127; \\
 a_8 &= 0.109; a_9 = 0.082; a_{10} = 0.046; S(\mathbf{a}) = 0.005.
 \end{aligned}$$

Given in Table 3 are the weights for $m = 3, 4, \dots, 21$ ($m - 1 = 2, 3, \dots, 20$). The plot of $s(\mathbf{a})$ against m is given in Figure 1. Also illustrated in Figure 1 is the fact that $s(\mathbf{a})$ follows an exponential distribution (Draper and Smith, 1999) given by

$$S(\mathbf{a}) = e^{0.2862 - 0.7156m + 0.0177m^2} ; R^2 = 0.99 \quad (4.11)$$

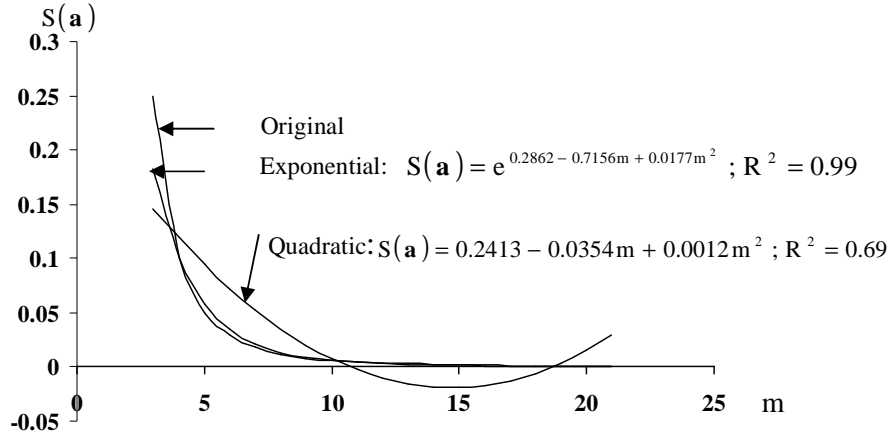


Figure 1: Plot of $S(\mathbf{a}) = \sum_{i=1}^{m-1} a_i^2 - \sum_{i=1}^{m-2} a_i a_{(i+1)}$ against m .

5. Simple Average of the CBE Derived Variables

Iwueze et al (2010) discussed the properties of the estimator based on the simple average (SAE: Simple average estimator) of the derived CBE variables given by

$$\hat{\mathbf{b}}^{(c)} = \frac{1}{(m-1)} \sum_{i=2}^m \hat{\mathbf{b}}_i^{(c)} \quad (5.1)$$

The mean and variance of (5.1) are:

$$E(\hat{\mathbf{b}}^{(c)}) = \mathbf{b} \quad (5.2)$$

$$\begin{aligned} \text{var}(\hat{\mathbf{b}}^{(c)}) &= \sigma_{\hat{\mathbf{b}}^{(c)}}^2 = \frac{1}{(m-1)^2} \left\{ \sum_{i=1}^{m-1} \text{var}(\hat{\mathbf{b}}_i^{(c)}) + 2 \sum_{i < j}^{m-1} \sum_{j}^{m-1} \text{cov}(\hat{\mathbf{b}}_i^{(c)}, \hat{\mathbf{b}}_j^{(c)}) \right\} \\ &= \frac{1}{(m-1)^2} \left\{ \sum_{i=1}^{m-1} \text{var}(\hat{\mathbf{b}}_i^{(c)}) - 2 \sum_{i=1}^{m-2} \text{cov}(\hat{\mathbf{b}}_i^{(c)}, \hat{\mathbf{b}}_{i+1}^{(c)}) \right\} \\ &= \frac{1}{(m-1)^2} \left\{ (m-1) \left(\frac{2\sigma^2}{s^3} \right) - (m-2) \left(\frac{2\sigma^2}{s^3} \right) \right\} \\ &\quad \text{(from (2.5) and (2.7))} \\ &= \frac{2\sigma^2}{(m-1)^2 s^3} \{m-1 - m+2\} = \frac{1}{(m-1)^2} \left(\frac{2\sigma^2}{s^3} \right) \end{aligned} \quad (5.3)$$

The SA estimate (5.1) is also a linear unbiased estimator of the slope (\mathbf{b}) parameter.

Comparing (4.6) and (5.3), we note that the difference between the variances of the SAE and the BLUE lies in the difference between $s(a) = \sum_{i=1}^{m-1} a_i^2 - \sum_{i=1}^{m-2} a_i a_{i+1}$ for the BLUE and $\frac{1}{(m-1)^2}$ for the SAE. Figure 2 illustrates the differences. The variance of the intercept (a) is given in Iwueze et al (2010) as:

$$\text{var}(\hat{a}) = \frac{\sigma^2}{n} + \left(\frac{n+1}{2}\right)^2 \text{var}(\hat{b}) \tag{5.4}$$

where $\hat{b} = \hat{b}^{(c)} = \frac{1}{(m-1)} \sum_{i=2}^m \hat{b}_i^{(c)}$ for the SAE and $\hat{b} = T = \sum_{i=1}^{m-1} a_i \hat{b}_i^{(c)}$ for the BLUE. At

$m = 3$, $s(a) = \left(\frac{1}{m-1}\right)^2$ so that variances of the estimates of the slope are the same for BLUE and SAE.

6. Empirical Examples

The first example are simulations (all simulations and computations in this section are done with MINITAB) of $n = 4m$ ($m = 8, 11, \dots, 18$) observations from $X_t = a + bt + S_t + e_t$ with $a = 1.0$, $b = 0.2$, $S_1 = -1.5$, $S_2 = 2.5$, $S_3 = 3.5$, $S_4 = -4.5$ and $e_t \sim N(0, 1)$. The properties of the BLUE were also determined and compared with those from the Least Squares Estimation method (LSE) and Simple Average method (SAE) of the Buys-Ballot derived variables.

As Table 4 shows, BLUE recovers the values of the slope and intercept used in the simulation better than the other two methods. The variances of the estimates of the slope and intercept are also smaller for the BLUE than for the other two methods

The autocorrelation function (acf) of the residuals obtained after decomposition using the LSE, SAE and BLUE methods were used to confirm the adequacy of the fitted models. Diagnostic checks on the residuals are discussed in Box et al (1994).

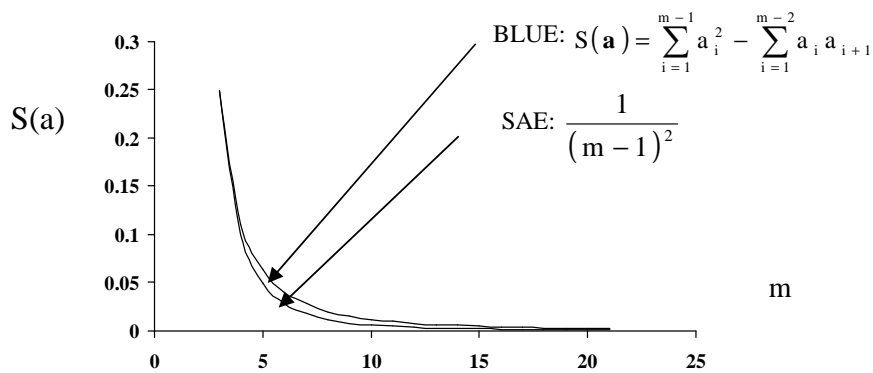


Figure 2: Plot of $s(a) = \sum_{i=1}^{m-1} a_i^2 - \sum_{i=1}^{m-2} a_i a_{(i+1)}$ and $\frac{1}{(m-1)^2}$ against m

Table 4: Summary of estimates of LSE, BLUE and SAE

m	Method	\hat{a}	\hat{b}	$\hat{\sigma}_a$	$\hat{\sigma}_b$	S_1	S_2	S_3	S_4	$\hat{\sigma}$
8	LSE	1.309	0.181	1.261	0.067	-1.322	2.534	3.439	-4.651	0.996
	SAE	1.490	0.170	0.459	0.025	-1.339	2.529	3.444	-4.634	1.029
	BLUE	1.084	0.195	0.361	0.019	-1.302	2.541	3.432	-4.671	0.977
9	LSE	1.174	0.191	1.196	0.056	-1.538	3.086	3.108	-4.656	0.875
	SAE	1.185	0.190	0.413	0.021	-1.539	3.086	3.108	-4.655	0.876
	BLUE	0.965	0.202	0.313	0.015	-1.521	3.092	3.102	-4.673	0.861
10	LSE	1.170	0.192	1.106	0.047	-1.347	2.403	3.518	-4.573	0.999
	SAE	0.615	0.219	0.185	0.020	-1.307	2.416	3.504	-4.614	1.019
	BLUE	1.006	0.200	0.170	0.014	-1.515	2.347	3.574	-4.406	1.004
11	LSE	1.666	0.193	1.109	0.043	-1.258	2.593	3.638	-4.973	0.963
	SAE	0.762	0.211	0.411	0.017	-1.231	2.602	3.629	-5.000	0.966
	BLUE	0.987	0.201	0.306	0.012	-1.246	2.597	3.634	-4.985	0.957
12	LSE	1.481	0.180	0.961	0.034	-1.288	2.180	3.476	-4.368	0.960
	SAE	1.478	0.181	0.403	0.015	-1.288	2.180	3.476	-4.368	0.960
	BLUE	1.360	0.185	0.296	0.011	-1.281	2.183	3.473	-4.375	0.958
13	LSE	1.199	0.193	1.026	0.034	-1.273	2.683	3.644	-5.054	0.947
	SAE	1.371	0.186	0.398	0.014	-1.283	2.680	3.648	-5.045	0.961
	BLUE	1.056	0.198	0.524	0.009	-1.265	2.686	3.642	-5.062	0.943
14	LSE	0.970	0.201	0.926	0.028	-1.393	2.622	3.363	-4.592	0.992
	SAE	0.726	0.210	0.407	0.013	-1.380	2.627	3.358	-4.605	0.992
	BLUE	0.852	0.205	0.259	0.008	-1.387	2.625	3.361	-4.598	0.990
15	LSE	1.265	0.191	0.847	0.024	-1.465	2.393	3.308	-4.236	0.982
	SAE	0.803	0.206	0.407	0.013	-1.443	2.401	3.301	-4.259	1.006
	BLUE	1.147	0.195	0.268	0.008	-1.460	2.395	3.306	-4.241	0.962
16	LSE	1.166	0.195	0.867	0.023	-1.114	2.520	3.375	-4.781	0.969
	SAE	1.358	0.189	0.396	0.012	-1.123	2.518	3.377	-4.772	0.983
	BLUE	1.036	0.199	0.213	0.005	-1.109	2.523	3.373	-4.787	0.967
17	LSE	1.130	0.193	0.848	0.021	-1.375	2.465	3.496	-4.586	1.144
	SAE	0.770	0.203	0.461	0.013	-1.359	2.470	3.490	-4.601	1.152
	BLUE	1.034	0.196	0.260	0.006	-1.370	2.466	3.494	-4.590	1.142
18	LSE	1.124	0.197	0.743	0.018	-1.424	2.280	3.217	-4.073	0.960
	SAE	0.919	1.044	0.382	0.010	-1.415	2.283	3.213	-4.081	0.962
	BLUE	1.044	0.199	0.226	0.005	-1.420	2.282	3.215	-4.077	0.959

The second example is the 32 consecutive quarters of U.S beer production, in millions of barrels, from first quarter of 1975 to the fourth quarter of 1982, and is listed as Series W10 in Wei (1990). In order to assess the forecasting performance of our models, we use only the first 30 observations of the series for model construction.

The estimates of the parameters using Least Squares Estimation method (LSE) are again determined and compared with those from the BLUE and SAE computed from the CBE derived variables. The computational procedure for the slope (b) is laid out in Table 5 while Table 6 gives the summary of the estimates.

Table 5: Buys-ballot table for U.S. beer production.

Year	Quarter				\bar{X}_i	$\hat{\sigma}_i$	$\hat{b}_i^{(c)}$	a_i	$a_i \hat{b}_i^{(c)}$
	I	II	III	IV					
1975	36.14	44.60	44.15	35.72	40.15	4.88	0.2550	0.083	0.0212
1976	36.19	44.63	46.95	36.90	41.17	5.43	0.3575	0.143	0.0511
1977	39.66	49.72	44.49	36.54	42.60	5.76	0.5425	0.179	0.0971
1978	41.44	49.07	48.98	39.59	44.77	4.97	0.3200	0.190	0.0608
1979	44.29	50.09	48.42	41.39	46.05	3.95	0.6800	0.179	0.1217
1980	46.11	53.44	53.00	42.52	48.77	5.35	- 0.0875	0.143	- 0.0125
1981	44.61	55.18	52.24	41.66	48.42	6.34	0.6600	0.083	0.0548
1982	47.84	54.27	-	-	51.06	4.55	-	-	-
\bar{X}_j	42.04	50.13	48.32	39.19	44.99				
$\hat{\sigma}_j$	4.42	4.07	3.46	2.78		5.66			

Table 6: Summary of estimates of LSE, BLUE and SAE for U. S beer production

Method	\hat{a}	\hat{b}	$\hat{\sigma}_a$	$\hat{\sigma}_b$	S_1	S_2	S_3	S_4	$\hat{\sigma}$
LSE	39.099	0.380	1.790	0.101	-2.692	5.018	3.592	-5.918	1.244
SAE	38.955	0.390	0.564	0.033	-2.297	5.403	3.207	-6.313	1.307
BLUE	38.885	0.394	0.461	0.025	-2.291	5.405	3.205	-6.319	1.311

Wei (1990), ignoring the stochastic trend in the series, used 30 observations of the series for Integrated Autoregressive Moving Average (ARIMA) model construction. Based on the forecasting performance of his models, he settled on the model

$$(1 - B^4)X_t = \underset{(\pm 0.09)}{1.49} + \left(1 - \underset{(\pm 0.16)}{0.87} B^4\right) e_t \quad (6.1)$$

with $\hat{\sigma}^2 = 2.39$.

The one step ahead and two step ahead forecasts, $\hat{X}_{30}(\ell)$ for $\ell = 1$ and 2 , from the forecast origin 30 are calculated for each estimation method. The forecast errors and the corresponding summary statistics used by Wei (1990) are shown in Table 7. With respect to Table 7, MPE is the Mean Percentage Error, MSE is the Mean Square Error, MAE is the Mean Absolute Error and MAPE is the Mean Absolute Percentage Error as defined in Wei (1990).

Table 7: Comparison of the forecasts between models

Lead time	Actual Value	Wei (1990)		LSE		SAE		BLUE	
		Forecast Value	Error	Forecast Value	Error	Forecast Value	Error	Forecast Value	Error
1	52.31	54.38	-2.07	54.48	-2.17	54.24	-1.93	54.31	-2.00
2	41.83	45.37	-3.54	45.35	-3.52	45.11	-3.28	45.18	-3.35
	MPE	-6.2%		-6.3%		-5.8%		-5.9%	
	MSE	8.4		8.6		7.2		7.6	
	MAE	2.8		2.9		2.6		2.7	
	MAPE	6.2%		6.3%		5.8%		5.9%	

The results of Table 7 indicate that the SAE and BLUE give approximate results that are better than those given by the LSE and ARIMA in terms of forecasts. This example illustrates the fact that sometimes a simple descriptive model computed from the Buys-Ballot procedure may be preferred to the more complicated ARIMA and LSE methods in a series where all the methods are adequate in terms of the residuals.

7. Concluding Remarks

This study has examined the Best Linear Unbiased Estimator (BLUE) of the slope (b) of a linear trend-cycle component of time series computed from the Buys-Ballot derived variables defined by Iwueze and Nwogu (2004). The emphasis on the slope is based on the fact that estimates of the other parameters (intercept and seasonal indices) depend on it. The properties of the BLUE were also determined and compared with those from the Least Squares Estimation method (LSE) and Simple Average method (SAE) of the Buys-Ballot derived variables.

The results show that of the two derived variables (CBE and FBE), only the CBE derived variable were found to be stationary (with constant mean and variance) but are correlated with only one significant autocorrelation coefficient at lag one. The derived variable from the FBE are non-stationary with constant autocorrelation coefficient at all lags. Hence, they are considered incapable, in their present state, to give any reliable estimate.

The variance of the BLUE for the slope (b) based on the CBE-derived variables was shown to depend on the sum of squares and cross-products $S(a)$ of the weights (a_i) of the derived variables. The values of $S(a)$, in turn, depend on the number of periods (m).

The variances of the estimates of the slope (the BLUE and SAE) are constant multiples of the variance of $\hat{b}_i \left(\frac{2\sigma^2}{s^3} \right)$. The multipliers are $\left(\frac{1}{m-1} \right)^2$ for SAE and $S(a)$ for the BLUE. At $m = 3$, $S(a) = \left(\frac{1}{m-1} \right)^2$ so that variances of the estimates of the slope are the same for BLUE and SAE. For $m > 3$, the variances appear to decay exponentially as m increased.

The estimate of the slope based on simple average is only a particular case of the BLUE in which all the weights are equal $\left(i.e., a_i = \frac{1}{m-1} \right)$. The multipliers of $\frac{2\sigma^2}{s^3}$ are, for every $m > 3$, greater for SAE than BLUE. This ensures that the BLUE has minimum variance. As a consequence, the variances of the estimates of the intercept (a) are for every $m > 3$, smaller for the BLUE than for the SAE. These are clearly supported by the results of the empirical examples shown in Table 4. Another important result is that (i) for $m > 3$, the error variance is smaller for the BLUE than for

the SAE and LSE and (ii) for most m the estimates of the slope (b) and intercept (a) from BLUE are closer to the actual values used in the simulation than those from SAE and LSE.

Therefore, when using Buys-Ballot procedure for time series decomposition, it is recommended that when trend-cycle component is linear, the BLUE for the slope computed from the CBE-derived variable be used. This leads to more precise estimates of time series components.

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